

①

## LECTURE 3

Extra remarks on Lindeberg method: non-linear functions, non-iid  $X_i$ .  
 (See previous notes for some details.)

Thm: (Lindeberg CLT)  $(X_{i,n})_{1 \leq i \leq n}$  independent,  $\mathbb{E}X_{i,n} = 0$ ,  $\mathbb{E}X_{i,n}^2 < \infty$   
 $V_n^2 := \text{Var} \sum_{i=1}^n X_{i,n} = \sum_{i=1}^n \mathbb{E}X_{i,n}^2$  (think  $V_n = O(\sqrt{n})$  usually)

Suppose Lindeberg condition holds:  $\forall \varepsilon > 0$ ,

$$\frac{1}{V_n^2} \sum_{i=1}^n \mathbb{E}X_{i,n}^2 \underbrace{\mathbb{1}\{|X_{i,n}| > \varepsilon V_n\}}_{\text{without this, just average variance.}} \rightarrow 0.$$

with it, "contribution to avg. variance of large deviation".

~~Then,~~  $\hat{S}_n := \frac{1}{V_n} \sum_{i=1}^n X_{i,n} \Rightarrow N(0, 1)$   
 ↪ (if  $\mathbb{E}X_{i,n}^2 = 1$ ,  $V_n = \sqrt{n}$ )



Ex:  $Y_{i,n}$  iid with  $\mathbb{E}Y_{i,n} = 0$ ,  $\mathbb{E}Y_{i,n}^2 = 1$ ,  $X_{i,n} = c_{i,n} Y_{i,n}$   
 $V_n^2 = \sum_{i=1}^n c_{i,n}^2$

$$(LHS) = \frac{1}{\sum_{i=1}^n c_{i,n}^2} \sum_i c_{i,n}^2 \mathbb{E}Y_{i,n}^2 \mathbb{1}\{|Y_{i,n}| > \varepsilon \sqrt{\sum_{j=1}^n c_{j,n}^2}\}$$

$$= \frac{1}{\sum_i c_{i,n}^2} \left( \sum_i c_{i,n}^2 \right) \mathbb{E}Y_{1,1}^2 \mathbb{1}\{|Y_{1,1}| > \varepsilon \sqrt{\sum_{j=1}^n c_{j,n}^2}\}$$

→ enough ~~to have~~ to have  $\frac{\|c\|_2}{\|c\|_\infty} \xrightarrow{\text{not } \infty} \infty$  (i.e., no one term contributes too much.)

Ex:  $X_{i,n} \stackrel{\text{iid}}{\sim} \text{Ber}(p_n)$ ,  $\bar{X}_{i,n} := X_{i,n} - \mathbb{E}X_{i,n} = X_{i,n} - p_n$   
 When does  $\frac{1}{V_n^2} \sum_i \bar{X}_{i,n} \xrightarrow{\text{?}} N(0, 1)$ ?

Intuition: so long as  $p_n$  not too small.

(2)

$$V_n^2 = n \cdot \text{Var } X_{1,n} = n \cdot p_n(1-p_n).$$

$$(\text{LHS}) = \frac{1}{np_n(1-p_n)} \sum_{i=1}^n \mathbb{E} (X_{i,n} - p_n)^2 \mathbb{1}_{\{|X_{i,n} - p_n| > \varepsilon \sqrt{np_n(1-p_n)}\}}$$

Say  $p_n \in [0, \frac{1}{2}]$  (otherwise, consider  $1-X_{i,n}$ ). Two cases:

(1)  $np_n \rightarrow \infty$ : then  $(\text{LHS}) = 0$  for  $n$  suff. large.

(2)  $np_n$  bounded: then, for  $\varepsilon$  suff. small,

$$(\text{LHS}) = \frac{1}{np_n(1-p_n)} \cdot n \cdot (1-p_n)^{\frac{1}{2}} \cdot p_n = 1-p_n \rightarrow 1.$$

Thm: If  $np_n \rightarrow \infty$ , then  $\frac{1}{V_n} \sum_i \bar{X}_{i,n} \rightarrow N(0,1)$ .  
 "even very rare events obey CLT".

Q: What about  $p_n = \frac{\lambda}{n}$ ?

$\xrightarrow{\text{Rk: Law}(S_n) = \text{Bin}(n, \frac{\lambda}{n})}$

$$S_n := \sum_{i=1}^n X_{i,n} \rightarrow \begin{cases} \mathbb{E} S_n = n \cdot \frac{\lambda}{n} = \lambda \\ \text{Var } S_n = n \cdot \frac{\lambda}{n} \left(1 - \frac{\lambda}{n}\right) \rightarrow \lambda \end{cases}$$

Def:  $P \sim \text{Pois}(\lambda)$  if  $P \in \{0, 1, 2, \dots\}$ ,  $\mathbb{P}[P=k] = \frac{\lambda^k}{k!} \exp(-\lambda)$ .

Thm: (PLT) If  $X_{i,n} \stackrel{\text{iid}}{\sim} \text{Ber}\left(\frac{\lambda}{n}\right)$ , then  $S_n \rightarrow \text{Pois}(\lambda)$ .  
 $\hookrightarrow \text{Rk: No normalization!}$

Pf: Enough to show  $\mathbb{P}[S_n = k] \rightarrow \mathbb{P}[P=k] = \frac{\lambda^k}{k!} \exp(-\lambda)$

$$\mathbb{P}[S_n = k] = \binom{n}{k} \left(\frac{\lambda}{n}\right)^k \left(1 - \frac{\lambda}{n}\right)^{n-k} = \frac{n(n-1)\dots(n-k+1)}{n \cdot n \dots n} \frac{\lambda^k}{k!}$$

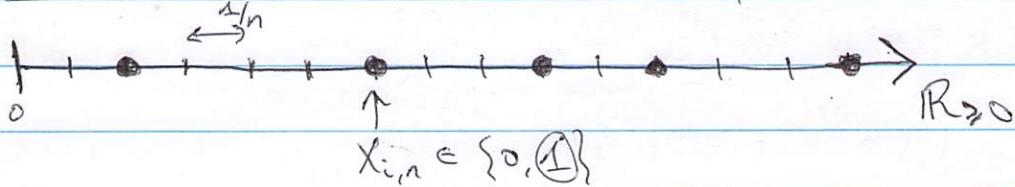
$$\left(1 - \frac{\lambda}{n}\right)^{-k} \left(1 - \frac{\lambda}{n}\right)^n \rightarrow \frac{\lambda^k}{k!} \exp(-\lambda)$$

③

"Poisson Point Process"



Preview of PPP: Consider  $X_{i,n} \stackrel{\text{ind}}{\sim} \text{Ber}\left(\frac{\lambda}{n}\right)$ ,  $i=1, 2, \dots, n, \dots$



For each  $n$ , defines  $\mu_n$  ~~is~~ prob. measure over subsets of  $R \geq 0$ .  
Will see later: in some sense, " $\mu_n \rightarrow \mu$ ", for  $\mu = \text{PPP}(\lambda)$ .

Previous analysis:  $A \sim \text{PPP}(\lambda) \Rightarrow \text{Law}(|A \cap [0, 1]|) = \text{Pois}(\lambda)$ .

Similarly,  $\text{Law}(|A \cap [x, y]|) = \text{Pois}(\lambda(y-x))$

$\text{Law}(|A \cap B|) = \text{Pois}(\lambda \cdot \text{Lebesgue measure of } B)$ .

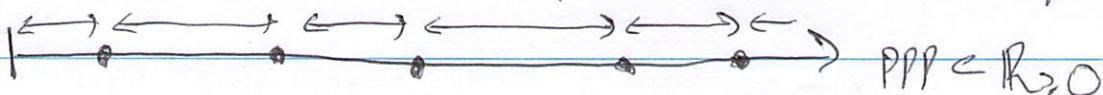
For now: consider spacings of points, e.g. first point:

$T_n := \min \{i : X_{i,n} = 1\}$ ,  $\hat{T}_n := \frac{T_n}{n}$  (= position of leftmost point of PPP.)

Thm:  $\hat{T}_n \Rightarrow \text{Exp}(\lambda)$  (Def:  $T \sim \text{Exp}(\lambda)$  has density  $\mathbb{1}_{\{x \geq 0\}} \lambda e^{-\lambda x}$ .)

$$\begin{aligned} \text{PF: } P[\hat{T}_n \leq t] &= 1 - P[\hat{T}_n > t] = 1 - P[T_n > tn] \\ &= 1 - \left(1 - \frac{\lambda}{n}\right)^{tn} \rightarrow 1 - \exp(-\lambda t). \end{aligned}$$

Ex:  $T_n^{(1)} := T_n$ ,  $T_n^{(k)} := (\text{k}^{\text{th}} \text{ smallest } i : X_{i,n} = 1) - ((k-1)^{\text{th}} \text{ smallest })$   
 $\hat{T}_n^{(k)} := \frac{1}{n} T_n^{(k)} \rightarrow T_n^{(k)} \Rightarrow \text{Exp}(\lambda)$ ,  
 $(T_n^{(1)}, \dots, T_n^{(k)}) \Rightarrow (\text{k independent Exp}(\lambda)'s)$ .



Standard modeling choice for "waiting" or "arrival" times.